



A continuum damage model for creep fracture and fatigue analysis

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Introduction



- Sustainable energy system is a combination of wide variety of energy resources.
- Result in flexible power generation.
- New requirements for boiler creep fatigue design due to intermittent power demand.



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Thermodynamic formulation

Developed models are completely defined by two potential functions:

the **specific Helmholtz free energy** $\psi = \psi(T, \epsilon_{te}, \omega)$,

(linear kinematics assumed $\epsilon = \epsilon_e + \epsilon_c + \epsilon_{th}$, $\epsilon_{te} = \epsilon - \epsilon_c$,
 $\omega = 1 - D$)

and the **complementary dissipation potential** $\varphi(Y, q, \sigma; T, \omega)$
 defined as

$$\gamma = \frac{\partial \varphi}{\partial \mathbf{q}} \cdot \mathbf{q} + \frac{\partial \varphi}{\partial \boldsymbol{\sigma}} : \boldsymbol{\sigma} + \frac{\partial \varphi}{\partial Y} Y.$$

Together with the Clausius-Duhem inequality

$$\gamma = -\rho(\dot{\psi} + s\dot{T}) + \boldsymbol{\sigma} : \dot{\boldsymbol{\epsilon}} - T^{-1} \text{grad}T \cdot \mathbf{q} \geq 0$$

results the constitutive equations

$$\begin{aligned} -\rho \left(s + \frac{\partial \psi}{\partial T} \right) \dot{T} + \left(\boldsymbol{\sigma} - \rho \frac{\partial \psi}{\partial \boldsymbol{\epsilon}_{te}} \right) : \dot{\boldsymbol{\epsilon}}_{te} + \left(\dot{\boldsymbol{\epsilon}}_c - \frac{\partial \varphi}{\partial \boldsymbol{\sigma}} \right) : \boldsymbol{\sigma} \\ - \left(\dot{\omega} + \frac{\partial \varphi}{\partial Y} \right) Y - \left(\frac{\text{grad}T}{T} + \frac{\partial \varphi}{\partial \mathbf{q}} \right) \cdot \mathbf{q} = 0. \end{aligned}$$



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Specific models

The specific Helmholtz free energy

$$\rho\psi = \rho c_\varepsilon \left(T - T \ln \frac{T}{T_r} \right) + \frac{1}{2} (\boldsymbol{\varepsilon}_{te} - \boldsymbol{\varepsilon}_{th}) : \boldsymbol{\omega} \mathbf{C}_e : (\boldsymbol{\varepsilon}_{te} - \boldsymbol{\varepsilon}_{th}),$$

$\boldsymbol{\varepsilon}_{th} = \boldsymbol{\alpha}(T - T_r)$, thermal strain, \mathbf{C}_e elasticity tensor, $\boldsymbol{\alpha}$ thermal expansion coefficients, T_r stress free reference temperature.

The complementary dissipation potential

$$\varphi(Y, \mathbf{q}, \boldsymbol{\sigma}; T, \omega) = \varphi_{th}(\mathbf{q}; T) + \varphi_d(Y; T, \omega) + \varphi_c(\boldsymbol{\sigma}; T, \omega),$$

where the thermal part is

$$\varphi_{th}(\mathbf{q}; T) = \frac{1}{2} T^{-1} \mathbf{q} \cdot \boldsymbol{\lambda}^{-1} \mathbf{q}.$$

For creep the following Norton type potential function is adopted

$$\varphi_c(\boldsymbol{\sigma}; T, \omega) = \frac{h_c(T)}{p+1} \frac{\omega \sigma_{rc}}{t_c} \left(\frac{\bar{\sigma}}{\omega \sigma_{rc}} \right)^{p+1},$$

$$\bar{\sigma} = \sqrt{3J_2}, \quad h_c(T) = \exp(-Q_c/RT).$$



Damage potential

Kachanov-Rabotnov type

$$\varphi_d(Y; T, \omega) = \frac{h_d(T)}{r+1} \frac{Y_r}{t_d \omega^k} \left(\frac{Y}{Y_r} \right)^{r+1}, \quad \text{model 1}$$

$$\varphi_d(Y; T, \omega) = \frac{h_c(T)}{(\frac{1}{2}p+1)(1+k+p)} \frac{Y_r}{t_d \omega^k} \left(\frac{Y}{Y_r} \right)^{\frac{1}{2}p+1}, \quad \text{model 2}$$

t_d is a characteristic time for damage evolution,
 $h_d(T) = \exp(-Q_d/RT)$, where Q_d is the damage activation energy and R is the universal gas constant. The reference value $Y_r = \sigma_{rd}^2/(2E)$, where σ_{rd} is a reference stress for the damage process.



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Monkman-Grant parameter

Experimental relationship

$$C_{MG} = (\dot{\epsilon}_{\min}^c)^m t_{rup} \approx \text{constant.}$$

For the two models the Monkman-Grant parameter have the values ($m = 1$)

$$C_{MG} = \dot{\epsilon}_{\min}^c t_{rup} = \frac{1}{1+k+2r} \frac{t_d h_c}{t_c h_d} \left(\frac{\sigma}{\sigma_r} \right)^{p-2r} \quad \text{model 1}$$

$$C_{MG} = \frac{t_d}{t_c} \quad \text{model 2.}$$

Model 2 can be obtained by imposing the following constraints to the model 1:

$$p = 2r, \quad \frac{1}{1+k+2r} \frac{t_d h_c}{t_c h_d} = \text{constant.}$$

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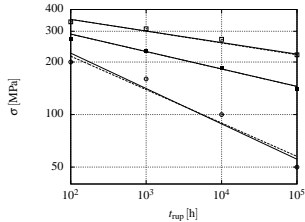
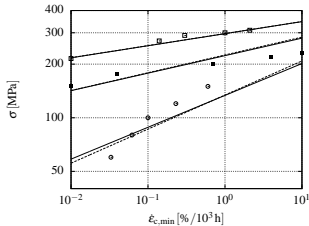
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T24 material parameters

The calibrated model parameters for the 7CrMoVTiB10-10 steel (T24), $q_c = Q_c/R$ and $q_d = Q_d/R$,
 $p(T) = p_r(1 + a(T - T_r)/T_r)$ and $r(T) = r_r(1 + b(T - T_r)/T_r)$,
 $\sigma_{rc} = \sigma_{rd} = \sigma_{y0}(T) = \sigma^* - cT$, with $\sigma^* = 1123$ MPa, $c = -1$ MPa/K.

mod	t_c [s]	p_r	t_d [s]	a	q_c [K]	r_r	q_d [K]	b
1	3039.9	14.77	37.768	-4.804	7137.6	7.545	9350.1	-5.201
2	3414.1	14.59	41.26	-4.891	7137.6	-	-	-



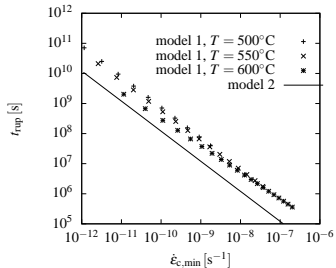
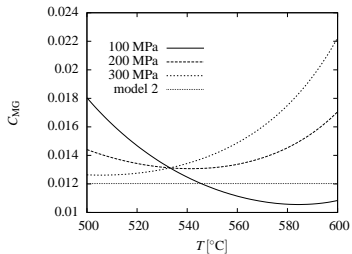
Minimum creep strain-rate (lhs) and the creep strengths (rhs).

Solid lines = model 1, dashed lines = model 2. Top 500°C, middle 550°C bottom 600°C.



Monkman-Grant parameter

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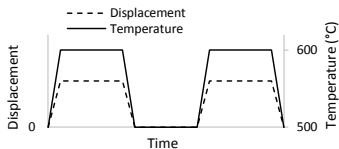
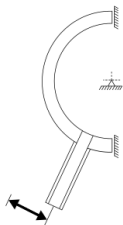
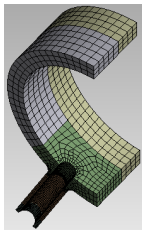
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FE analysis and results

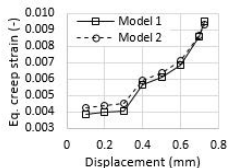
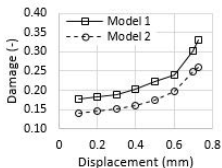
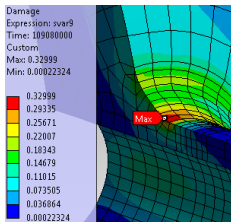
The models are implemented in ANSYS using the USERMAT subroutine and the mesh consists of mainly 20 node hexahedral ANSYS SOLID186 elements & some 10 node tetrahedral SOLID187 elements. Prescribed displacement history at the end of the tube nozzle.

The computed lifetime is roughly 150 cycles. Ramp time 1 hour and hold time 200 hours. Internal pressure 14 MPa.



Results

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Damage distribution near the most critical location of the header. The accumulated damage and the equivalent creep strain at the most critical location as functions of the prescribed displacement.



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Concluding remarks

- Thermodynamically consistent model for high-temperature creep fatigue analyses has been developed.
- A specific model with Norton-Bailey type creep and Kachanov-Rabotnov type damage models are used.
- Two version of the damage evolution equations. One-version satisfies the Monkman-Grant hypothesis exactly.
- Materials parameters for the 7CrMoVTiB10-10 steel (T24) have been estimated in the temperature range 500-600 °C.
- Developed models have been implemented in the ANSYS FE-software by using the USERMAT subroutine.

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Thank You for Your Attention!



Etna the Living Mountain
Oil painting on canvas by Gilda Gubiotti 2008.

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