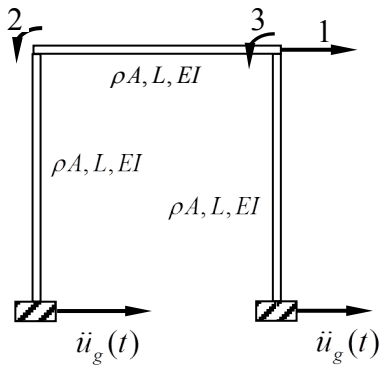


1. Määritä kuvan tasapaksun ja homogeenisen sauvan alimmat ominaiskulmataajuudet käyttämällä
 - a) tarkkaa ratkaisua,
 - b) yhtä sauvaelementtiä ja konsistenttia massamatriisia,
 - c) yhtä sauvaelementtiä ja keskitettyä massamatriisia,
 - d) kahta sauvaelementtiä ja konsistenttia massamatriisia,
 - e) kahta sauvaelementtiä ja keskitettyä massamatriisia,



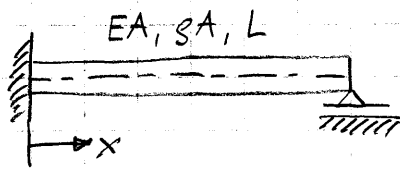
2. Alustaan vaikuttaa maanjäristyksessä tunnettu kiihtyvyysheräte $\ddot{u}_g(t)$. Käytä aikaisempien harjoitusten ratkaisua ja esitä järjestelmän liikeyhtälöt. Kerro miten laskisit kyseisen tehtävän? Voit myös ratkaista tehtävän vaikkapa vakioisella alustan kiihtyvyysherätteellä.

$$\mathbf{M} = \frac{\rho AL}{420} \begin{bmatrix} 732 & 22L & 22L \\ 22L & 8L^2 & -3L^2 \\ 22L & -3L^2 & 8L^2 \end{bmatrix}$$

$$\mathbf{K} = \frac{EI}{L^3} \begin{bmatrix} 24 & 6L & 6L \\ 6L & 8L^2 & 2L^2 \\ 6L & 2L^2 & 8L^2 \end{bmatrix}$$

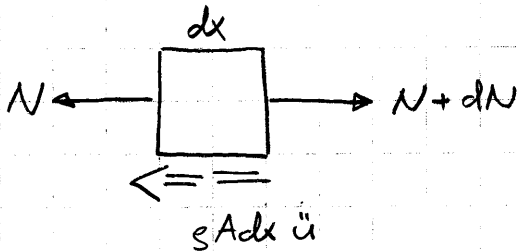
Rak. dyn.

①



sauvaelementti

②



$$\sum F \Rightarrow: -N + N + dN - sAxü = 0 \quad ||: dx$$

$$\frac{dN}{dx} - sAxü = 0$$

$$\sigma = \frac{N}{A} = E\varepsilon \Rightarrow N = E\varepsilon A = EA \frac{du}{dx} \Rightarrow \frac{dN}{dx} = EA \frac{d^2u}{dx^2}$$

$$L_0 = dx$$

$$L = dx + du$$

$$\varepsilon = \frac{L - L_0}{L_0} = \frac{dx + du - dx}{dx} = \frac{du}{dx}$$

ODY: $EA \frac{d^2u}{dx^2} - sAxü = 0$

grite: $\tilde{u} = \hat{u} \sin(\omega t)$

$$\ddot{\tilde{u}} = -\omega^2 \hat{u} \sin(\omega t)$$

$$\frac{E}{s} \frac{d^2 \hat{u}}{dx^2} \sin(\omega t) + \omega^2 \hat{u} \sin(\omega t) = 0$$

$$\frac{E}{s} \hat{u}'' + \omega^2 \hat{u} = 0$$

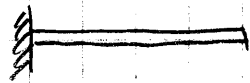
$$\hat{u}'' + \frac{\omega^2 s}{E} \hat{u} = 0$$

grite: $\hat{u} = C_1 \cos\left(\omega \sqrt{\frac{s}{E}} x\right) + C_2 \sin\left(\omega \sqrt{\frac{s}{E}} x\right)$

$$\hat{u}' = -\omega \sqrt{\frac{s}{E}} C_1 \sin\left(\omega \sqrt{\frac{s}{E}} x\right) + \omega \sqrt{\frac{s}{E}} C_2 \cos\left(\omega \sqrt{\frac{s}{E}} x\right)$$

①/2

reunachdot.



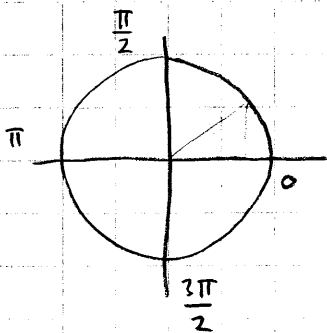
$$u(0) = 0 \Rightarrow C_1 = 0$$

$$u'(L) = \omega \sqrt{\frac{S}{E}} C_2 \cos\left(\omega \sqrt{\frac{S}{E}} L\right) = 0$$

$$\cos\left(\omega \sqrt{\frac{S}{E}} L\right) = 0 \rightarrow \omega L \sqrt{\frac{S}{E}} = \frac{\pi}{2}, \frac{3\pi}{2}, \frac{5\pi}{2}, \dots$$

$$= \left(\frac{\pi}{2} + n\pi\right) \quad n = 0, 1, 2, \dots$$

$$= (2n+1) \frac{\pi}{2}$$



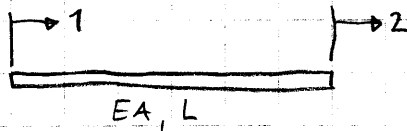
\Rightarrow

$$\omega = (2n+1) \frac{\pi}{2} \sqrt{\frac{E}{SL^2}}, \quad n = 0, 1, 2, 3, \dots$$

$$\omega_1 = 1,571 \sqrt{\frac{E}{SL^2}}$$

$$\omega_2 = 4,712 \sqrt{\frac{E}{SL^2}}$$

sauva elementti

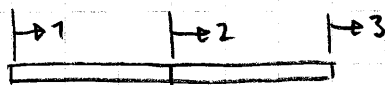


$$[K^e] = \frac{EA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}, \quad [m^e]_L = \rho AL \begin{bmatrix} 1/2 & 0 \\ 0 & 1/2 \end{bmatrix}, \quad [m^e]_c = \frac{\rho AL}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

b) $\frac{EA}{L} - \omega^2 \frac{\rho AL}{3} = 0 \Rightarrow \omega = \sqrt{3} \sqrt{\frac{E}{\rho L^2}} \approx 1,732 \sqrt{\frac{E}{\rho L^2}} \quad (+10,2\%)$

c) $\frac{EA}{L} - \omega^2 \frac{\rho AL}{2} = 0 \Rightarrow \omega = \sqrt{2} \sqrt{\frac{E}{\rho L^2}} \approx 1,414 \sqrt{\frac{E}{\rho L^2}} \quad (-7,9\%)$

kaksi elementtiä



d) $[K] = \frac{EA}{L} \begin{bmatrix} 4 & -2 \\ -2 & 2 \end{bmatrix} \quad [M_c] = \frac{\rho AL}{12} \begin{bmatrix} 4 & 1 \\ 1 & 4 \end{bmatrix}$

$$\det(K - \lambda M) = 0 \Rightarrow \begin{vmatrix} 4 - 4\tilde{\lambda} & -2 - \tilde{\lambda} \\ -2 - \tilde{\lambda} & 2 - 2\tilde{\lambda} \end{vmatrix} = 0 \quad \tilde{\lambda} = \frac{\omega^2 \rho 4L^2}{12 EA}$$

$$\Rightarrow 8 - 16\tilde{\lambda} + 8\tilde{\lambda}^2 - (4 + 4\tilde{\lambda} + \tilde{\lambda}^2) = 0$$

$$7\tilde{\lambda}^2 - 2\tilde{\lambda} + 4 = 0 \Rightarrow \tilde{\lambda}_1 = 0,2164$$

$$\tilde{\lambda}_2 = 2,6408$$

$$\Rightarrow \omega_1 \approx 1,611 \sqrt{\frac{E}{\rho L^2}} \quad (+2,5\%)$$

$$\omega_2 \approx 5,629 \sqrt{\frac{E}{\rho L^2}} \quad (+19,5\%)$$

ominaisvektorit: $\phi_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1 \end{bmatrix} \quad \phi_2 = \begin{bmatrix} -1/\sqrt{2} \\ 1 \end{bmatrix}$

$$e) [M]_L = \frac{5AL}{4} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{vmatrix} 4-2\tilde{\lambda} & -2 \\ -2 & 2-\tilde{\lambda} \end{vmatrix} = 0 \quad \tilde{\lambda} = \frac{\omega^2}{4} \frac{5AL^2}{EA}$$

$$\Rightarrow 2\tilde{\lambda}^2 - 8\tilde{\lambda} + 4 = 0 \quad \Rightarrow \tilde{\lambda}_1 = 0,586$$

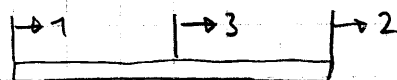
$$\tilde{\lambda}_2 = 3,414$$

$$\Rightarrow \omega_1 \approx 1,531 \sqrt{\frac{E}{9L^2}} \quad (-2,5\%)$$

$$\omega_2 \approx 3,696 \sqrt{\frac{E}{5L^2}} \quad (-21,6\%)$$

$$\{\tilde{\phi}_1\} = \begin{bmatrix} 1/\sqrt{2} \\ 1 \end{bmatrix} \quad \{\tilde{\phi}_2\} = \begin{bmatrix} -1/\sqrt{2} \\ 1 \end{bmatrix}$$

f) kolmisolmuinen sauva



$$N_1(x) = 1 - 3\frac{x}{L} + 2\left(\frac{x}{L}\right)^2$$

$$N_{1,x} = \frac{1}{L} (-3 + 4\frac{x}{L})$$

$$N_2(x) = -\frac{x}{L} + 2\left(\frac{x}{L}\right)^2$$

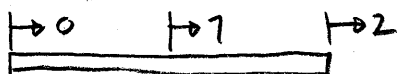
$$N_{2,x} = \frac{1}{L} (-1 + 4\frac{x}{L})$$

$$N_3(x) = 4\frac{x}{L} - 4\left(\frac{x}{L}\right)^2$$

$$N_{3,x} = \frac{1}{L} (4 - 8\frac{x}{L})$$

$$k_{ij} = \int_0^L EA N_{i,x} N_{j,x} dx \Rightarrow [k^e] = \frac{EA}{3L} \begin{bmatrix} 7 & 1 & -8 \\ 1 & 7 & -8 \\ -8 & -8 & 16 \end{bmatrix} \begin{matrix} 0 \\ 1 \\ 2 \end{matrix}$$

$$m_{ij} = \int_0^L 5AN_i N_j dx \Rightarrow [m^e] = \frac{5AL}{30} \begin{bmatrix} 4 & -1 & 2 \\ -1 & 4 & 2 \\ 2 & 2 & 16 \end{bmatrix} \begin{matrix} 0 \\ 1 \\ 2 \end{matrix}$$



$$[K] = \frac{EA}{3L} \begin{bmatrix} 7 & -8 \\ -8 & 16 \end{bmatrix} \quad [M] = \frac{5AL}{30} \begin{bmatrix} 4 & 2 \\ 2 & 16 \end{bmatrix}$$

$$\det (K - \omega^2 M) = 0$$

$$\Rightarrow \omega_1 \approx 1,577 \sqrt{\frac{E}{sL^2}} \quad (+0,4\%)$$

$$\omega_2 \approx 5,673 \sqrt{\frac{E}{sL^2}} \quad (+20,4\%)$$

d) orijon slično valitnom $\bar{g} = 200 \frac{EI}{SAL^4} = \bar{g} \frac{EI}{SAL^4}$

$$\hat{K} = K - \bar{g}M = \frac{EI}{L^3} \begin{bmatrix} -324,57 & -4,4762L & -4,4762L \\ -4,4762L & 4,1305L^2 & -3,42806L^2 \\ -4,4762L & 3,4286L^2 & 4,1305L^2 \end{bmatrix}$$

$L=1$

write

$$\hat{\phi} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\hat{y} = M \hat{\phi} = \begin{pmatrix} 1,7429 \\ 0,026190 \\ 0,07857 \end{pmatrix}$$

$$\lambda = \lambda \frac{SAL^4}{EI}$$

$$\hat{\bar{\phi}} = \hat{K}^{-1} \hat{y} = \begin{pmatrix} -0,0054707 \\ -0,030714 \\ 0,0380597 \end{pmatrix} \quad (K - \lambda M) = (\bar{K} - \lambda \bar{M})$$

$$= [(\bar{K} - \bar{g} \bar{M}) - \hat{\lambda} \bar{M}]$$

$$\hat{\bar{\omega}} = M \hat{\bar{\phi}} = \begin{pmatrix} -0,0091511 \\ -0,0011433 \\ 0,00065732 \end{pmatrix}$$

$$\hat{\lambda} = \bar{\lambda} - \bar{g}$$

$$\hat{\bar{\lambda}} = \frac{\hat{\bar{\omega}}^T \hat{\bar{\omega}}}{\hat{\bar{\omega}}^T \hat{\bar{\omega}}} = -66,714$$

$$\hat{y} = \frac{\hat{\bar{\omega}}}{\sqrt{\hat{\bar{\omega}}^T \hat{\bar{\omega}}}} = \begin{pmatrix} -0,87181 \\ -0,108918 \\ 0,06262 \end{pmatrix}$$

2. korak

$$\hat{\bar{\phi}} = \hat{K}^{-1} \hat{y} = \begin{pmatrix} 0,002756 \\ -0,114010 \\ 0,111136 \end{pmatrix}$$

$$\hat{\bar{\omega}} = M \hat{\bar{\phi}} = \begin{pmatrix} 0,0045999 \\ -0,0028226 \\ 0,003074 \end{pmatrix}$$

$$\hat{\bar{\lambda}} = \frac{\hat{\bar{\omega}}^T \hat{\bar{\omega}}}{\hat{\bar{\omega}}^T \hat{\bar{\omega}}} = 25,15$$

$$\bar{\lambda}_2 = \hat{\bar{\lambda}} + \bar{g} = 25,15 + 200 = 225,15$$

$$\lambda_2 = \bar{\lambda}_2 \frac{EI}{SAL^4} = 225,15 \frac{EI}{SAL^4}$$

$$\lambda_2^{\text{tablica}} = 229,09 \frac{EI}{SAL^4}$$

$$\omega_2 = 14,90 \sqrt{\frac{EI}{SAL^4}}$$

$$\phi_2^{\text{tablica}} = \begin{pmatrix} 0 \\ 4,369/L \\ -4,369/L \end{pmatrix}$$

$$\phi_2 = \frac{\hat{\bar{\omega}}}{\sqrt{\hat{\bar{\omega}}^T \hat{\bar{\omega}}}} = \begin{pmatrix} 0,1048 \\ -4,385/L \\ -4,274/L \end{pmatrix}$$

