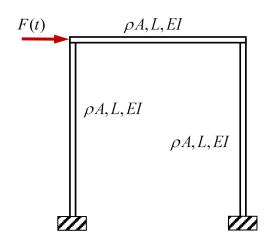


1. Determinate the stiffness matrix using two beam elements. Condense statically the rotational DOF. Determinate the lowest eigenpair by the inverse vector iteration. Use the lumped mass approximation. By Sturm's sequence rule find out whether the second eigenfrequency is higher than $\omega = 35\sqrt{EI/\rho AL^4}$.



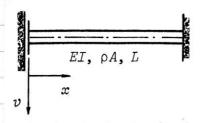
2. Use the eigenpair in Exercise 1 and determinate the steady state response when

$$\rho A = 6.0 \text{ kg/m}, \frac{EI}{L^3} = 1,346 \text{ kN/m},$$

 $L = 3 \text{ m (IPE } 80)$

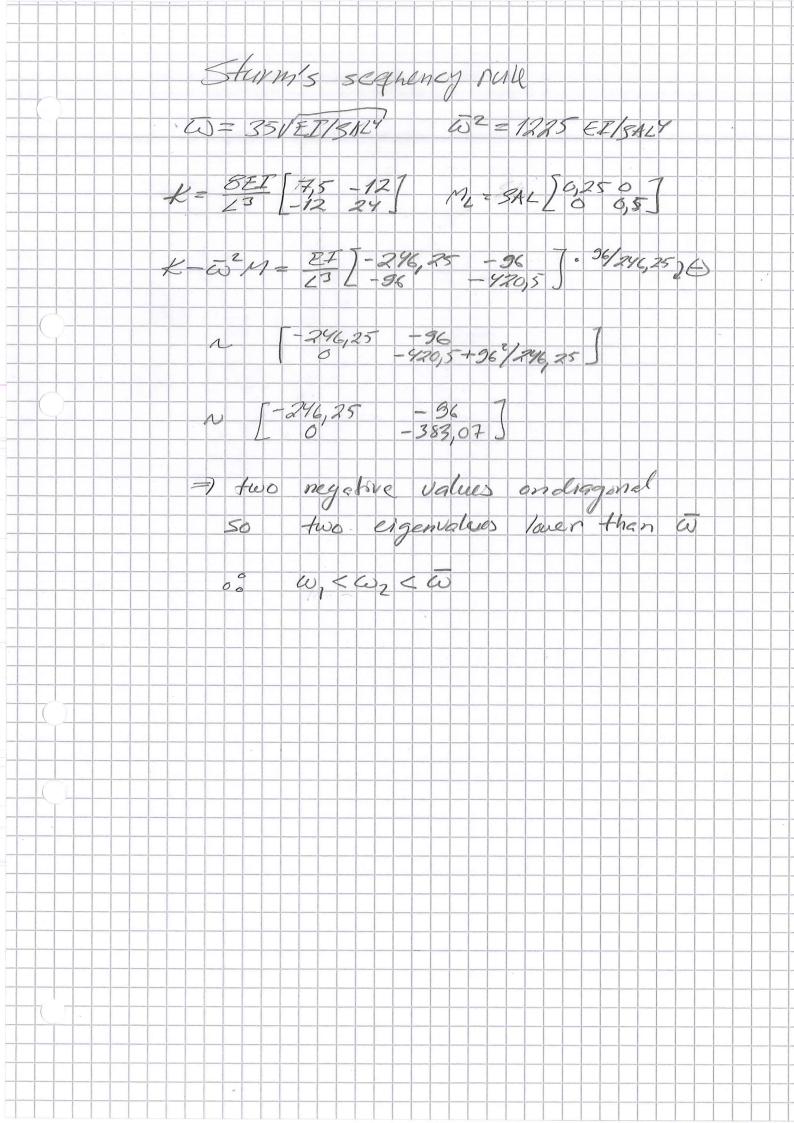
with the harmonic excitation

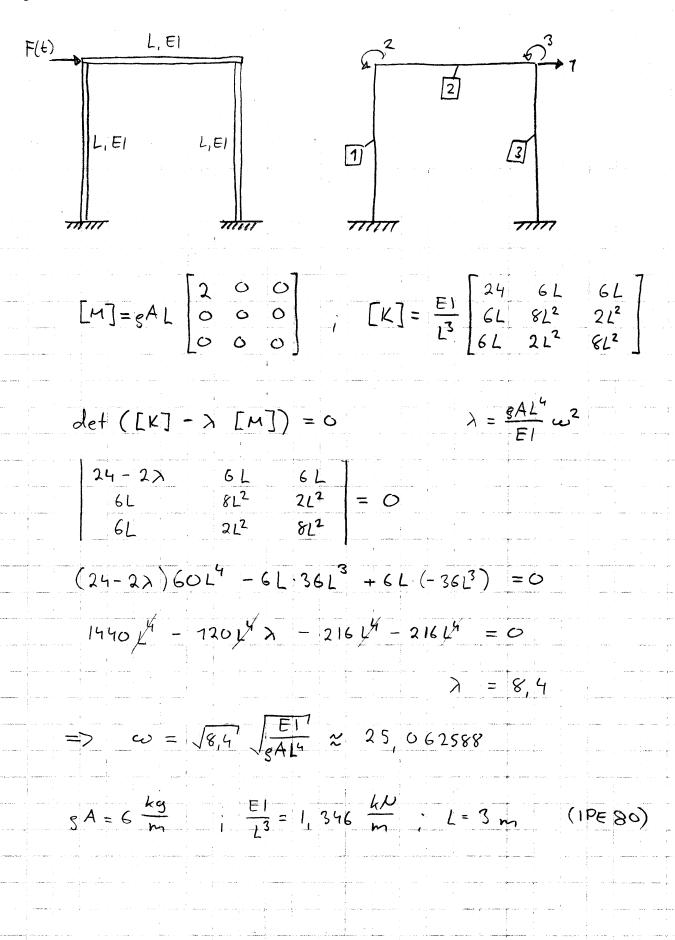
$$F(t) = 200\sin(25 \cdot t) \text{ N}.$$



Muodosta kuvan toisesta päästään jäykästi ja toisesta johteella tuetun tasapaksun ja homogeenisen palkin kahta elementtiä käyttävä laskentamalli. Tiivistä rotaatiovapausaste pois ja määritä palkin kaksi alinta ominaiskulmataajuutta. Käytä keskitettyä massamatriisia.

Mucros matrix ikration El X & = JMB 9= XEME NE-KING => 1 8 = K-(n/6/0) The first trial & cor = () L'MB = EP (0,03125) = 1 L'MB = EP (0,016329) = 32,00 EI/SALY (0,59167) 2 = (1,54167) = L My = 3AL (0,632/18) = 1 (1) EL (0,017476) = 3/135(0,5439) 90 = (0,5435) K-1490 (0,03216) 31,897 (0,5440) 2 = 31,857 EZ/SALY E,= (0,540) approximation for 1st eigenpair Layleigh quotient (6/003 setter approx.) De= 0746 = 31,0872 7p= 31,087 EZ/SAL w,=/12 = 5,576. 7/ ER/8451





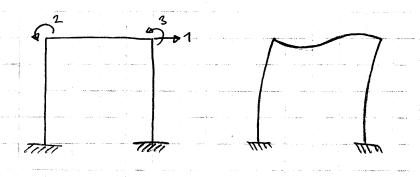
ominaismuoto:

$$\begin{bmatrix} 8L^2 & 2L^2 \\ 2L^2 & 8L^2 \end{bmatrix} \begin{bmatrix} \phi_2 \\ \phi_3 \end{bmatrix} = \begin{bmatrix} -6L \\ -6L \end{bmatrix} \Rightarrow \begin{bmatrix} 8 & 2 \\ 2 & 8 \end{bmatrix} \begin{bmatrix} \phi_2 \\ \phi_3 \end{bmatrix} = \begin{bmatrix} -6/L \\ -6/L \end{bmatrix}$$

$$\begin{bmatrix} \phi_{2} \\ \phi_{3} \end{bmatrix} = \begin{bmatrix} 8 & 2 \\ 2 & 8 \end{bmatrix} \begin{bmatrix} -\frac{6}{L} \\ -\frac{6}{L} \end{bmatrix} = \frac{1}{64 - 4} \begin{bmatrix} 8 & -2 \\ -2 & 8 \end{bmatrix} \begin{bmatrix} -\frac{6}{L} \\ -\frac{6}{L} \end{bmatrix}$$

$$\begin{bmatrix} \phi_2 \\ \phi_3 \end{bmatrix} = \frac{1}{60} \begin{bmatrix} -36/L \\ -36/L \end{bmatrix} = -\frac{3}{5L} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -0.6/L \\ -0.6/L \end{bmatrix}$$

$$\varphi = \begin{bmatrix} 1 \\ -0.6/L \\ -0.6/L \end{bmatrix}$$



$$\frac{1}{\phi_1} = \frac{1}{\sqrt{\phi^T M \phi^T}} \phi = \frac{1}{\sqrt{28AL}} \begin{bmatrix} 1 \\ -0.6/L \\ -0.6/L \end{bmatrix}$$

$$gAL = 184g$$

$$\mathcal{F} = \vec{\phi}_1^T \begin{bmatrix} F_1(t) \\ 0 \end{bmatrix} = \frac{1}{\sqrt{2gAL}} F_1(t) = \frac{1}{\sqrt{2gAL}} \cdot 200 \sin(2st) N$$

$$=\frac{100}{3}\sin{(25t)}$$
 N

va hvistuc kerroin

$$V = \frac{1}{1 - \left(\frac{\Omega}{\omega}\right)^2} = \frac{1}{1 - \left(\frac{25}{25.062588}\right)^2} = 200,469108$$

3/2

$$\frac{7}{21} + \lambda \frac{7}{1} = \frac{100}{3} \sin(25t)$$
; $\lambda = 8.4 \frac{E1}{5414} = 628,73 \frac{1}{52}$

$$[\tilde{n}] = \int kg \frac{m}{s^2}$$
 $[n] = \int kg m \qquad [F] = \int kg \frac{m}{s^2}$

$$\ddot{x} + \omega^2 x = \dot{F}(t) \sin(2st) \qquad \dot{F} = \frac{100}{3}$$

$$\Rightarrow \hat{F} = \times_{st} \omega^2 \qquad \times_{st} = \frac{\hat{F}}{\omega^2} = 0,053067 \sqrt{kg} \text{ m}$$

$$q_{st} = \hat{\phi} \times_{st} = \frac{1}{\sqrt{2}sAL} \begin{bmatrix} 1 \\ -0.6/L \\ -0.6/L \end{bmatrix} \cdot 0.053067 \text{ Jkg}^{\prime} \text{ m}$$
18kg

n=25 rads

$$\begin{array}{ll}
q &= \begin{bmatrix} 6,8445 & mm \\ -1,7685 \cdot 15^{3} \\ -1,7685 \cdot 10^{-3} \end{bmatrix} \\
\end{array}$$

$$q = \oint \frac{X_{st}}{1 - \left(\frac{\Omega}{\omega}\right)^2} \sin\left(\Omega t\right)$$

$$= \underset{-5t}{q} V \sin(\Omega t) \qquad V = 200,46$$